

#### General

Modern industrial applications require increasingly high performances from their pneumatic components. For example, the speed and thrust of a pneumatic cylinder, or the torque of a rotary actuator may need to be varied. These parameters often need to be modified dynamically while an operation is running.

Traditional solutions based upon pneumatic valves supplied with different pressures often take up excessive amounts of space. An alternative solution is a regulator that can vary pressure over time. This type of regulator is known as an electronically controlled proportional regulator. Three sizes have been designed, with flow rates of 7, 1,100 and 4,000 NI/min.

### Application fields.

Typical applications will include the necessity to dynamically control the force of an actuator, be it thrust or torque.

Examples include: Closing systems, painting systems, tensioning systems, packaging systems, pneumatic braking systems, force control for welding grippers, thickness compensation systems, balancing systems, laser cutting, pressure transducers for the control of modulating valves, test benches for system testing, force control for buffers on polishers, etc.

### **Product presentation**

The supply and exhaust connections are on one side of the regulator and the working port is on the opposite side. The two remaining sides carry G1/8" ports that are blanked off with removable plugs, these can be used to connect a pressure gauge or as an outlet port. If you order the version with the external feedback there is a M5 threaded connection to which connect the feedback pressure (to the pressure transducer). This connection is placed on the outlet connection side. This option allows to take the signal from a remote point instead of directly from the outlet connection; this function is typically used when the regulated pressure is used far away to the regulator. The control solenoid valves, the pressure sensor, and the management electronics are placed in upper part of the regulator.

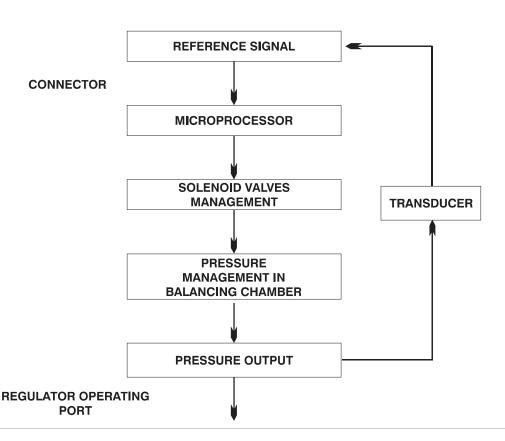
The electronic management system is the same for all the size 0, size 1 and size 3 regulators. The new proportional regulator range has all the features that were only optional on the previous model. When placing your order it is only necessary to specify the type of control signal, Voltage (T) or current (C), and the pressure range required.

# +24VDC 0 VDC 0-10 VDC / 4-20 mA OUTPUT MICROPROCESS.

**Functional diagram** 

#### CLOSED LOOP diagram (internal control circuit)

The proportional regulator is known as a CLOSED LOOP regulator because a pressure transducer in the circuit transmits a continuous analog signal to the microprocessor, which compares the reference value with the detected value and supplies the control solenoid valves accordingly.

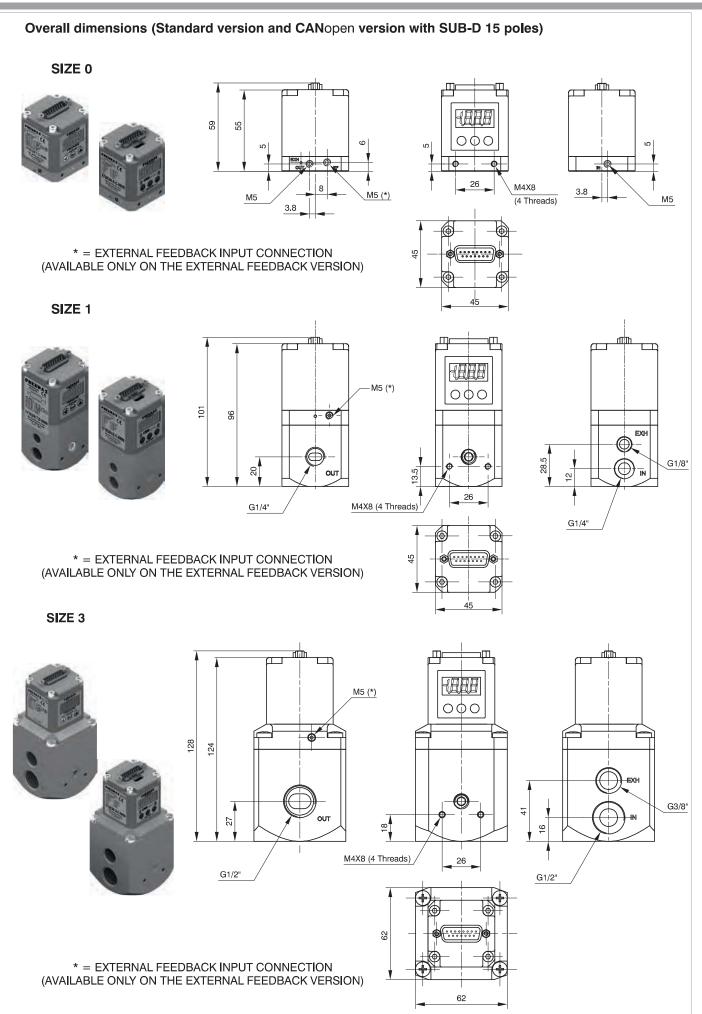


Series 1700 Size 1 - 3

# **Features**

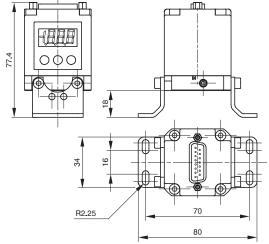
	Fluid		Air filtered	at 5 micron and	dehumidified	<u> </u>	
	Minimum inlet pressure		Air filtered at 5 micron and dehumidified  Desired outlet pressure + 1 bar				
	Maximum inlet pressure		10 bar				
	waximum injet pressure		Ordering code 0009 0005 0001				
	Outlet pressure		Pressure value	0 - 9 bar	0005 0 - 5 bar	0 - 1 bar	
	Nominal flowrate from 1 to 2 (6 bar Δp 1 bar)		Size 0	Size 1		Size 3	
			7 NI /min	1.100 NI /min	4.00	4.000 NI/min	
	Discharge flowrate		7 NI /min	1.300 NI /min	4.50	4.500 NI/min	
L	(at 6 bar with 1 bar overpressure)			1.000 141 / 111111	7.5		
L	Air consumption		< 1 NI/min	< 1 NI/min	<	< 1 NI/min	
L	Supply connection		M5	G 1/4"		G 1/2"	
L	Operating connection		M5	G 1/4"		G 1/2"	
L	Exhaust connection		Ø1,8	G 1/8"		G 3/8"	
	Maximum fitting tightening		3 Nm	15 Nm		15 Nm	
	Supply voltage		24VDC $\pm$ 10% (stabilised with ripple <1%)				
	Standby current consumption		55 mA				
	Current consumption with solenoid valves on		145 mA				
	Reference signal	Voltage	*0 - 10 V *0 - 5 V *1 - 5 V				
		Current	*4 - 20 mA *0 - 20 mA				
	Input impedance	Voltage	10 ΚΩ				
		Current	250 Ω				
	Voltage analog output		*0 - 10 V *0 - 5 V				
	Current analog output		*4 - 20 mA *0 - 20 mA				
	Digital inputs		24VDC ± 10%				
	Digital outputs		24 VDC PNP (max current 50 mA)				
	Connector		D-sub 15 poles				
	Linearity		$<\pm$ 0,3 % F.S.				
	Hysteresis		<0,3 % F.S.				
	Repeatability		< ± 0,3 % F.S.				
	Sensitivity		< ± 0,3 % F.S.				
	Assembly position		Indifferent				
	Protection grade		IP65 (with casing fitted)				
	Ambient temperature		-5° - 50°C / 23° - 122°F				
	Body		Anodised aluminium				
	Shutters		Brass with vulcanised NBR				
	Diaphragm		Cloth-covered rubber				
	Seals		NBR				
	Cover for electrical part		Technopolymer				
	Springs		AISI 302				
	Weight		Size 0	Size 1		Size 3	
	<b>9</b>		168 gr.	360 gr.	3	350 gr.	





# Mounting options (Standard version and CANopen version with SUB-D 15 poles)

In addition to mounting directly using the M4 tappings on the body, the 170M5 bracket may also be used, as shown below:





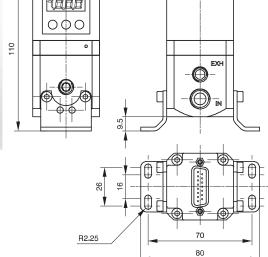
SIZE 0

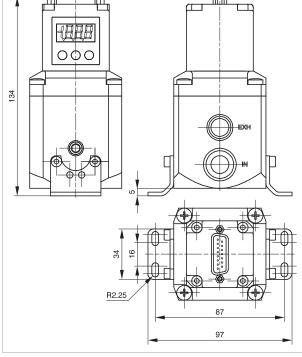


SIZE 1







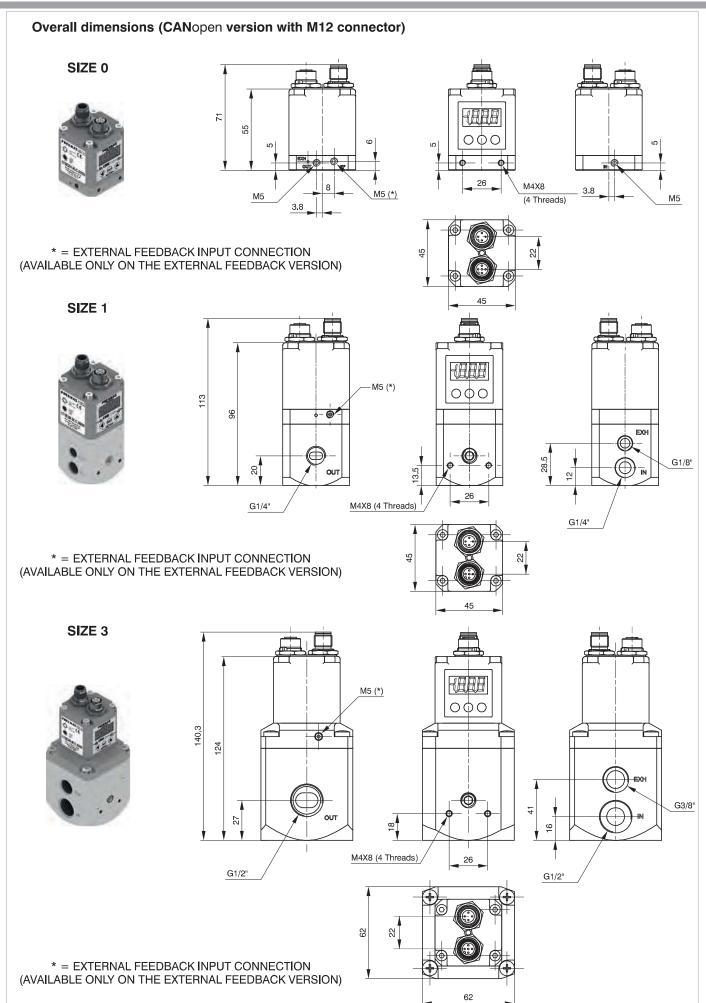




SIZE 3

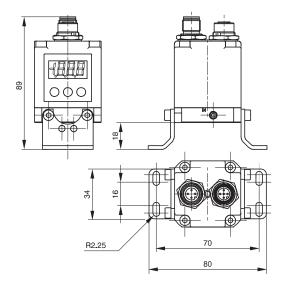






# Mounting options (CANopen version with M12 connector)

In addition to mounting directly using the M4 tappings on the body, the 170M5 bracket may also be used, as shown below:

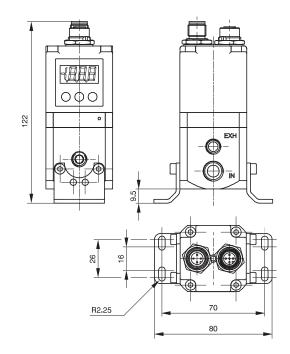


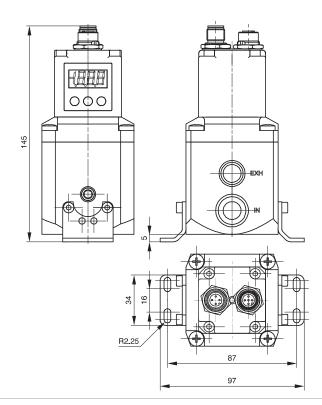
SIZE 0



SIZE 1

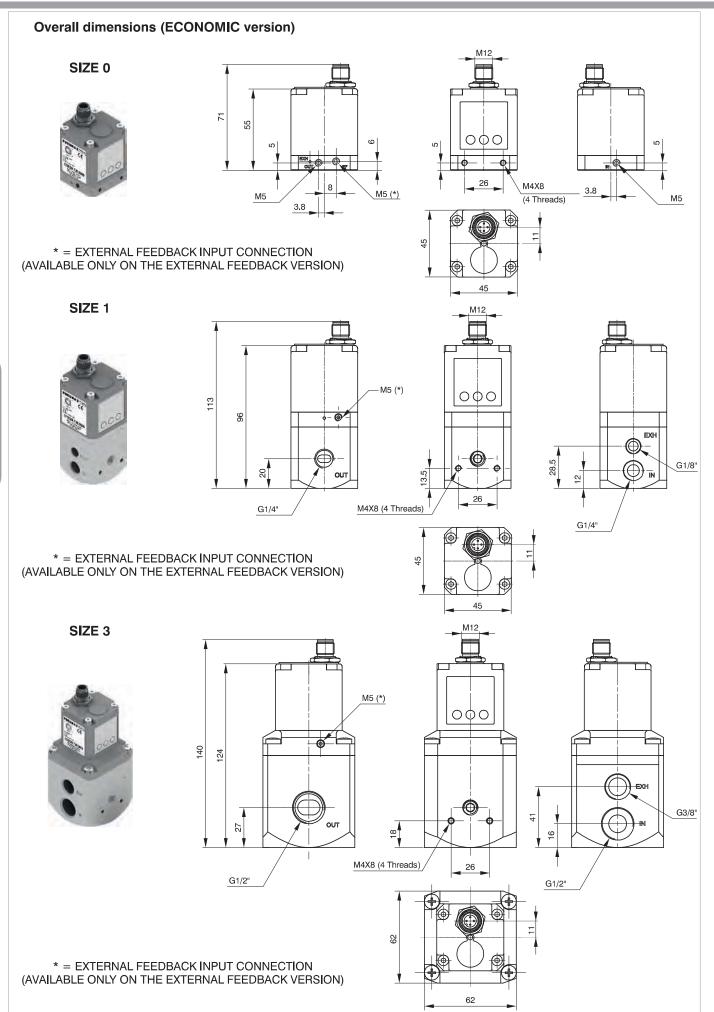






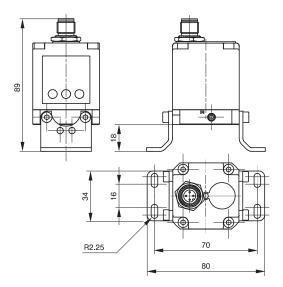






# **Mounting options (ECONOMIC version)**

In addition to mounting directly using the M4 tappings on the body, the 170M5 bracket may also be used, as shown below:

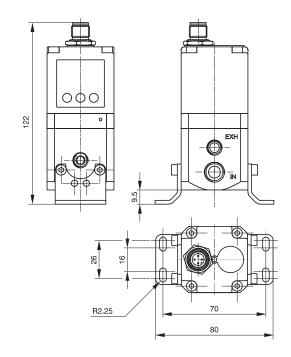


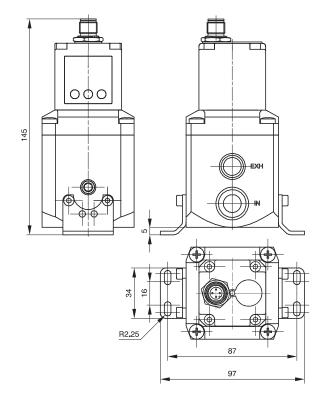
SIZE 0



SIZE 1









SIZE 3



## Installation/Operation

#### PNEUMATIC CONNECTION



The compressed air is connected by means of M5 threaded holes (for size 0 regulators), G 1/4" threaded holes (for size 1 regulators) and G 1/2" threaded holes (for size 3 regulators) on the body.

Before making the connections, eliminate any impurities in the connecting pipes to prevent chippings or dust entering the unit. Do not supply the circuit with more than 10 bar pressure and make sure that the compressed air is dried (excessive condensate could cause the appliance to malfunction) and filtered at 5 micron. The supply pressure to the regulator must always be at least 1 bar greater than the desired outlet pressure.

If a silencer is applied to the discharge path the unit response time may change; periodically check that the silencer is not blocked and replace it if necessary.

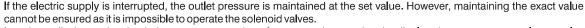


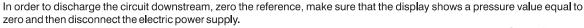
#### **ELECTRICAL CONNECTION**

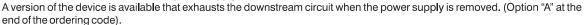
For the electrical connection a SUB-D 15-pole female or a M12 connector is used (accordingly to the model, to be ordered separately). Wire in accordance with the wiring diagram shown below.

Warning: INCORRECT CONNECTIONS MAY DAMAGE THE DEVICE

#### **NOTES ON OPERATION**







If the compressed-air supply is suspended and the electric power supply is maintained a whirring will be heard that is due to the solenoid valves; an operating parameter can be activated (P18) that triggers the regulator protection whenever the requested pressure is not reached within 4 seconds of the reference signal being sent. In this case the system will intervene to interrupt the control of the solenoid valves. Every twenty seconds, the unit will start the reset procedure until standard operating conditions have been restored.

# **TOP VIEW OF THE REGULATOR CONNECTOR**

#### Standard version 0000000 0 0 0 0 0 0 0 15*/* CONNECTOR PIN: = DIGITAL INPUT 1 = DIGITAL INPUT 2 = DIGITAL INPUT 3 = DIGITAL INPUT 4 = DIGITAL INPUT 5 = DIGITAL INPUT 6 = DIGITAL INPUT 7 7 = ANALOG INPUT / **DIGITAL INPUT 8** = SUPPLY (24 VDC) 10 = DIGITAL OUTPUT (24 VDC PNP) 11 = ANALOG OUTPUT (CURRENT) 12 = ANALOG OUTPUT (VOLTAGE) 13 = Rx RS-232 14 = Tx RS-232 15 = GND

# **CAN**open version with SUB-D 15 poles

**CONNECTOR PIN:** 1 = CAN\_SHLD  $2 = \overline{CAN} V +$  $3 = CAN_{\overline{G}ND}$  $4 = \overline{CAN} H$  $5 = CAN_L$ 6 = NC7 = NC8 = NC9 = SUPPLY (24 VDC) 10 = CAN SHLD  $11 = C\overline{A}N V +$ 12 = CAN GND  $13 = CAN_H$ 14 = CAN\_L 15 = GND

#### **ECONOMIC** version

### **CONNECTOR PIN:**

= SUPPLY (24 VDC) 1

= NC

3 = GND

= ANALOG INPUT











# **CAN**open version with M12 connector

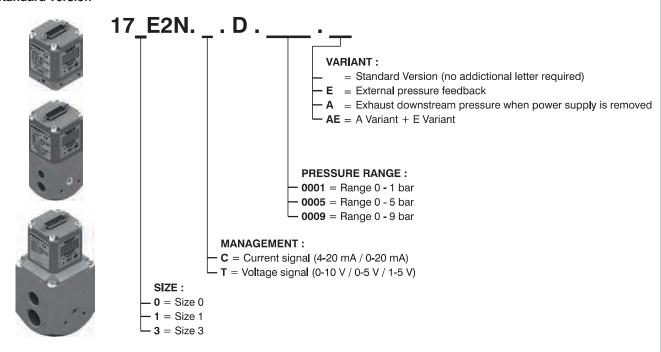
MALE CONNECTOR PIN: 1 = +24 VDC2 = NC3 = GND4 = NC**FEMALE CONNECTOR PIN:** 

1 = CAN SHLD 2 = CAN V+

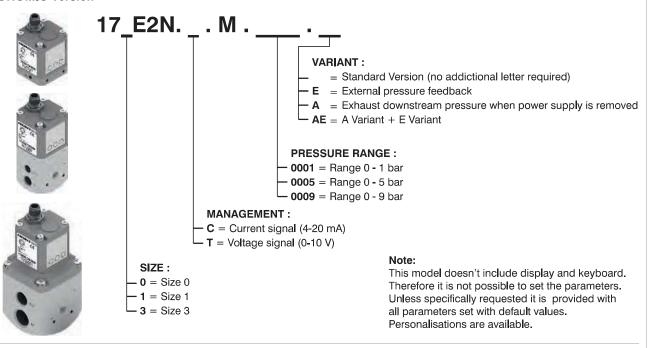
 $3 = CAN_{\overline{G}ND}$  $4 = \overline{CAN} H$ 

5 = CAN L

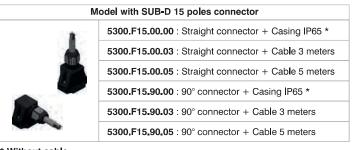
# ORDERING CODES Standard version



# ORDERING CODES ECONOMIC Version



# **Accessories**



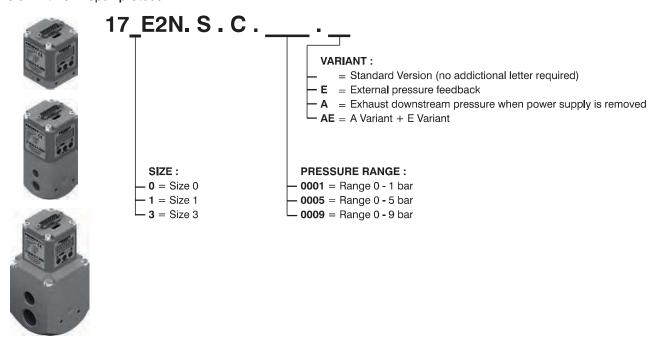




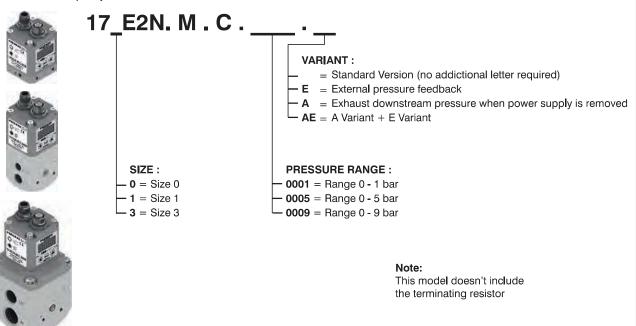
\* Without cable



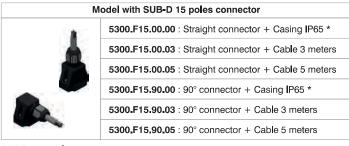
# ORDERING CODES Version with CANopen protocol



ORDERING CODES
Version with CANopen protocol M12 connector



# **Accessories**



\* Without cable





